

Homework 11 - Calculus of variations

Q11.1. The action functional

$$S[x(t)] = \int_{t_i}^{t_f} L(x, \dot{x}, t) dt \quad (\text{Q11.1.1})$$

can be varied either covariantly

$$\frac{\delta S}{\delta x^{\mathbf{a}}} = \frac{\partial L}{\partial x^{\mathbf{a}}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^{\mathbf{a}}} \right) \quad (\text{Q11.1.2})$$

or with respect to the coordinate paths

$$\frac{\delta S}{\delta x^\alpha} = \frac{\partial L}{\partial x^\alpha} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^\alpha} \right) \quad (\text{Q11.1.3})$$

(a) Show that

$$\frac{\delta S}{\delta x^{\mathbf{a}}} = \frac{\delta S}{\delta x^\alpha} e_{\mathbf{a}}^\alpha \quad (\text{Q11.1.4})$$

(b) Evaluate Eqs. (Q11.1.2) and (Q11.1.3) for

$$L = \frac{1}{2} m g_{\mathbf{ab}} \dot{x}^{\mathbf{a}} \dot{x}^{\mathbf{b}} - V(x) \quad (\text{Q11.1.5})$$

and show that they are equivalent.

A11.1. (a)

$$\begin{aligned} \frac{\delta S}{\delta x^{\mathbf{a}}} &= \frac{\partial L}{\partial x^{\mathbf{a}}} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^{\mathbf{a}}} \right) \\ &= \frac{\partial L}{\partial x^\alpha} e_{\mathbf{a}}^\alpha + \frac{\partial L}{\partial \dot{x}^\alpha} \dot{e}_{\mathbf{a}}^\alpha - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^\alpha} e_{\mathbf{a}}^\alpha \right) \\ &= \left[\frac{\partial L}{\partial x^\alpha} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^\alpha} \right) \right] e_{\mathbf{a}}^\alpha \\ &= \frac{\delta S}{\delta x^\alpha} e_{\mathbf{a}}^\alpha \end{aligned} \quad (\text{A11.1.1})$$

(b)

$$L = \frac{1}{2} m g_{\mathbf{ab}} \dot{x}^{\mathbf{a}} \dot{x}^{\mathbf{b}} - V(x) \quad (\text{A11.1.2})$$

therefore

$$\begin{aligned} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^{\mathbf{a}}} \right) - \frac{\partial L}{\partial x^{\mathbf{a}}} &= \frac{d}{dt} (m g_{\mathbf{ab}} \dot{x}^{\mathbf{b}}) + \frac{\partial V}{\partial x^{\mathbf{a}}} \\ &= m g_{\mathbf{ab}} \ddot{x}^{\mathbf{b}} + \nabla_{\mathbf{a}} V \end{aligned} \quad (\text{A11.1.3})$$

In components

$$L = \frac{1}{2} m g_{\gamma\delta} \dot{x}^\gamma \dot{x}^\delta - V(x) \quad (\text{A11.1.4})$$

therefore

$$\begin{aligned}
\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}^\alpha} \right) - \frac{\partial L}{\partial x^\alpha} &= \frac{d}{dt} (mg_{\alpha\beta} \dot{x}^\beta) - \frac{1}{2} m \frac{\partial g_{\gamma\delta}}{\partial x^\alpha} \dot{x}^\gamma \dot{x}^\delta + \frac{\partial V}{\partial x^\alpha} \\
&= m \dot{x}^\epsilon \frac{\partial g_{\alpha\beta}}{\partial x^\epsilon} \dot{x}^\beta + mg_{\alpha\beta} \ddot{x}^\beta - \frac{1}{2} m \frac{\partial g_{\gamma\delta}}{\partial x^\alpha} \dot{x}^\gamma \dot{x}^\delta + \frac{\partial V}{\partial x^\alpha} \\
&= mg_{\alpha\beta} \ddot{x}^\beta + \frac{1}{2} m \left(\frac{\partial g_{\alpha\gamma}}{\partial x^\delta} + \frac{\partial g_{\alpha\delta}}{\partial x^\gamma} - \frac{\partial g_{\gamma\delta}}{\partial x^\alpha} \right) \dot{x}^\gamma \dot{x}^\delta + \frac{\partial V}{\partial x^\alpha} \\
&= mg_{\alpha\beta} \left(\ddot{x}^\beta + \Gamma_{\gamma\delta}^\beta \dot{x}^\gamma \dot{x}^\delta \right) + \frac{\partial V}{\partial x^\alpha} \tag{A11.1.5}
\end{aligned}$$

which is the component form of Eq. (A11.1.3).